



level of  $w_l = 50\%$ . The starting point counter of the modulated pulse is defined by  $\tau_l$  and the modulation depth by  $k$ .

As spreading code we consider Walsh-Hadamard (WH) codes, of which we apply all except the “all ones” code word. The remaining code words are DC-free and contain a small amount of low frequency components. The latter results in suppressed visibility of the embedded data. The code length determines the number of LEDs that can be uniquely identified and that can transmit data in the system, i.e. for a code length  $N$  the system supports  $N - 1$  LEDs. The chip detection can be based on the average light power over a  $T_2$  block or on the on-off pattern on a  $T_1$  level. Advantageously, the first approach requires a receiver bandwidth of  $1/T_2$  instead of  $1/T_1$ .

To support more lamps in the system, LEDs can additionally be identified by the start of the pulse in a block  $\tau_l$ . The resulting scheme is a hybrid code and time division multiple access (CTDMA) solution. The number of pulse start positions equals  $N_s = T_2/T_1$ , where  $1/T_1$  typically is in the order of 1 MHz and  $N_s$  will be larger than  $2^{10}$ . As a result, the number of uniquely addressable LEDs is  $N_s N/k$ . Typically this is larger than 10,000, thereby fulfilling requirement d). We note that CTDMA requires a receiver bandwidth of  $1/T_1$ .

After propagation through the channel, the individual light intensity from the  $l$ th LED at the sensor location is given by  $g_l$ . The resulting electrical signal, received with a photodetector (PD) with a responsivity of  $\varepsilon$ , is input to a receiver. After matched filtering the incoming signal, this receiver correlates it with the WH codebook. The resulting signal-to-noise ratio (SNR), after despreading, equals

$$\text{SNR}_l = N k g_l^2 \varepsilon^2 / (4 \sigma_n^2), \quad (1)$$

where  $\sigma_n^2$  is the variance of the sum of shot and thermal noise. For a threshold detector this results in a BER of

$$\text{BER}_l = (1/2) \text{erfc}(\sqrt{\text{SNR}_l}/2), \quad (2)$$

and a mean squared error (MSE) in estimation of the illumination contribution  $g_l$  using the least-squares estimator of

$$\sigma_{\text{LSE}}^2 = g_l^2 / \text{SNR}_l. \quad (3)$$

Figure 2 illustrates the BER and MSE results for the CTDMA-PWM modulation for three color lighting LEDs, in a system with 10,000 LEDs spaced regularly on the ceiling, see [7]. We can observe that the communication link is almost errorless up to a range  $r_l$  of 10.7, 9.3 and 8.1 m for the red, green, and blue LEDs, respectively. A normalized MSE (N-MSE) of  $10^{-2}$  is achieved for distances up to 12.5, 10.7 and 9.3 m, respectively. Beyond these ranges, the sensor moves away from the center of the LED light beam and performance decreases fast. The variation in performance for the different color LEDs can be attributed to the difference in LED light output power and the color dependence of the PD responsivity.

#### IV. ASYNCHRONOUS CDMA SOLUTION

When applying the solution of Section III, the different LEDs in the system require synchronization, which forms a clear disadvantage. Loss of synchronization severely affects

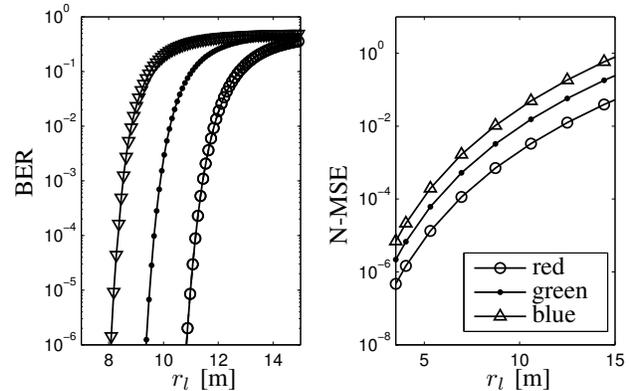


Fig. 2. BER (left) and MSE (right) performance vs. LED-PD propagation distance for red, green and blue LEDs. Ceiling height  $h = 3.5$  m.

system performance. Since synchronization may not be available for every system, we also developed an asynchronous VLC CDMA solution. This solution is reviewed here.

Different types of pseudonoise (PN) codes can be applied to encode and decode data in VLC. In contrast to the codes in Section III, these codes are not perfectly orthogonal, however, they have a low crosscorrelation for all possible timing offsets. The latter makes them specifically suitable for asynchronous operation. Also here the codes are embedded with the PWM method illustrated in Fig. 1, meeting requirements a) and c).

The main disadvantage of this MA solution is that it has to deal with multiple access interference (MAI), i.e. the contributions from other light sources are not fully suppressed. This will result in a decreased SNIR, given by

$$\text{SNIR}_l = \frac{N k g_l^2 \varepsilon^2}{4(\sigma_n^2 + \varepsilon^2 \sum_{m \neq l} g_m \rho_{ml}^2)}, \quad (4)$$

where  $\rho_{ml}$  denotes the correlation between the  $m$ th and  $l$ th code. This decreased SNIR results in an increased BER and MSE, using (2) and (3). We can conclude from (4) that a PN code needs to be much longer than a synchronous code, to match the performance of a synchronous solution. This is especially true since, according to requirement d), many LEDs need to be allocated. The resulting increased detection time and lower data rate, make such solution unsuitable for several applications. Moreover, to meet requirement b), additional constraints are imposed on the set of PN codes, to avoid low frequency components in the illumination signals.

#### V. CONCLUSIONS

We showed how CDMA can be applied for MA in VLC using PWM modulation, and how both proposed solutions meet the key system requirements. We foresee that extensions in asynchronous CDMA will enable more VLC applications.

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